



ANN-Based Adaptive PI Control for Wind Turbine with Doubly Fed Induction Generator

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Abstract—This paper focuses on developing a novel algorithm which dynamically optimizes the controllers of doubly fed induction generator (DFIG) driven by a wind turbine (WT) to increase DFIG transient performance in all wind speed conditions. Particle swarm optimization (PSO) is proposed to optimize parameters of PI controllers of DFIG's rotor side/grid side converters (RSC/GSC) at different wind speeds in order to maximize the damping ratios of the system eigenvalues in small signal stability analysis. Based on the optimal values and the wind speed data set, an artificial neural network (ANN) is designed, trained, and it has the ability to quickly forecast the optimal values of parameters. Adaptive PI controllers (including ANN) are designed which dynamically change PI gain values according to different wind speeds. Simulation is done via PSCAD software for a single machine connected to an infinite bus (SMIB) system. The results show that the DFIG of ANN-based adaptive PI control could significantly contribute in the transient performance improvement in a wide wind speed range.

Index Terms—Particle swarm optimization, DFIG, small signal stability, artificial neural network, damping ratio, optimal control, transient performance, and PSCAD

I. INTRODUCTION

Wind power capacity is growing at the rate of 20% annually on the average in the world, and its cost has decreased 50% in the last 10 years [1]. The quickly increasing widespread use of wind power extensively reduces carbon emissions, reduces the effect on global warming, and cuts down the dependence on fossil fuels.

With the rapid developments in power electronics, DFIG-WTs are very popular and the worldwide market share of DFIG is approximately 30% in recent years because of the advantages of higher efficiency, operation in a wide range, reactive power production, lower cost, and flexible control [2-6].

With the increasing high penetration of wind power, DFIG plays a more important role in power systems stability, and the improvement of DFIG transient performance is becoming increasingly significant. Previous researchers have attempted to improve this by developing different algorithms in the past

authors proved that adding a power system stabilizer to wind farms could significantly influence network damping. In [10], the authors presented an energy capacitor system with a fuzzy-controlled reference signal adjuster in the converter control to smoothen the output fluctuation. Others developed an algorithm to design the optimal PI controllers for the side converter to improve the transient performance [11]. Authors in [12] developed PSO to design the optimal PI controllers for the rotor side converter and grid side converter of DFIG for a particular wind speed. More recently, authors in [13] presented Bacteria Foraging technique to separately optimize the parameters of DFIG and the damper controller to increase the damping of low frequency oscillations of DFIG in three different wind speeds.

However, all of the approaches so far only optimize controller parameters at one special operating point (optimal model) and the parameters are constant. These controllers don't have the ability to dynamically adjust gain values according to the wind speed difference. Since these approaches are based on SMIB system and the inductance of transmission lines and multi-machines are neglected.

The proposed ANN-based adaptive PI control for DFIG is designed to improve DFIG transient performance. PSO is used to optimize PI parameters of DFIG's rotor and grid side converters at different operating points (different wind speeds) in order to maximize the damping ratios of the system eigenvalues in small signal stability analysis. Based on the calculated optimal values and the given wind speed data set, a two-layer feed-forward artificial neural network is designed and trained. The calculation for optimization and training is relatively slow and is done off-line. After that, ANN has the ability to quickly forecast the optimal values at each wind speed. The calculation for prediction is relatively fast and is done on-line. A sensor captures the wind speed which is ANN's input, and ANN forecasts the optimal value of PI parameters. It outputs them into the smart PI controllers. The controllers dynamically change values according to the different wind speeds to increase DFIG transient performance in a